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$$M = \frac{m_1 m_2}{m_1 + m_2}$$

$$\hat{F}(\ell) = \left(\frac{M\ell^2}{\ell}\right)^2 \frac{2}{\mu} \left(E - U - \frac{\ell^2}{2\mu\ell^2}\right) = \underbrace{2EM\ell^4 - \ell^2 \left(1 + \frac{22M}{\ell^2}\right)}_{EA}$$

$$= A^2 \ell^2 \left(\ell^2 - B^2\right)$$

$$= A^2 \ell^2 \left(\ell^2 - B^2\right)$$

$$A^2 = \frac{MN^2M}{M^2\ell^2N^2} = \frac{1}{\ell^2}$$

$$A^2 B^2 = 1 + \frac{2 \lambda \mu}{\mu^2 \ell^2 N^2} = 1 + \frac{\lambda}{\ell^2 E}$$

$$\Delta Y = 2 \int \frac{de}{\sqrt{A^2 e^2 (e^2 R^2)}} = \frac{2}{A} \int \frac{de}{e \sqrt{e^2 - R^2}}$$

$$e = 3 \times 4$$

$$de = 3 \times 4$$

$$= \frac{2}{AB} \int_{1}^{\infty} \frac{dx}{x \sqrt{x^{2}-1}} = \frac{T}{AB} = \frac{T}{\sqrt{1+\frac{2}{\ell^{2}E}}}$$

$$\widehat{C} = \pi - \Delta \Psi = \pi \left(1 - \frac{1}{\sqrt{1 + \frac{2}{\ell^2 E}}} \right)$$

$$= T \left(1 - \left(1 - \frac{1}{2 \ell^2 E} \right) \right) = T \frac{1}{2 \ell^2 E}$$

$$= 2 \ell^2 = T \frac{9^2}{2 \ell^2}$$

$$\frac{dB}{dQ} = \frac{1}{2\sin\theta} \frac{dR^2}{dQ^5} = \frac{\pi}{4} \frac{9^2}{Q^3}$$

SKRIPT:
$$lon\Theta_L = \frac{\sin \widetilde{\Theta}}{\cos \widetilde{\Theta} + K}$$
 KLEINE $\widetilde{\Theta} \Rightarrow \widetilde{\Theta}_L = \frac{\widetilde{\Theta}}{1 + K}$

$$l^{2} = \frac{\pi}{2} \frac{9^{2}}{3} = \frac{\pi}{2} \frac{9^{2}}{9!} \frac{1}{1+K}$$

$$K = \frac{m_y}{m_z}$$

$$\Rightarrow \frac{d\mathcal{B}}{d\Omega_{L}} = \frac{\pi}{4} \frac{9^{2}}{(1+\mu)\Theta_{L}^{3}}$$

$$\frac{dN}{dt} = eN \int \frac{dG}{d\Omega} d\Omega =$$

$$2w.0,702$$

$$ev_{2\pi} = \frac{9^{2}}{4} \left(\frac{1}{1+k} \right) \frac{9^{2}}{9^{3}} de = \frac{17^{2}}{2} ev_{\frac{9^{2}}{1+k}} = \frac{1}{2} \left(\frac{1}{Q_{1}} - \frac{1}{Q_{2}} \right)$$

$$\Theta_{1}$$

$$(4.3)$$

$$X^{2} + y^{2} + (2 - NE)^{2} - R^{2} = 0$$

$$X = R \sin \Theta \cos \Psi$$

$$Y = R \sin \Theta \sin \Psi$$

$$Z = R \cos \Theta + W = E$$

$$\dot{X} = R \dot{\Theta} \cos \Theta \cos \Psi - R \dot{\Psi} \sin \Theta \sin \Psi$$

$$\dot{Y} = R \dot{\Theta} \cos \Theta \sin \Psi + R \dot{\Psi} \sin \Theta \cos \Psi$$

$$\dot{Z} = -R \dot{\Theta} \sin \Theta + W$$

$$T = \frac{1}{2} m \left(\dot{X}^2 + \dot{Y}^2 + \dot{Z}^2 \right) =$$

$$= \frac{1}{2} m \left(R^2 \dot{\Theta}^2 + R^2 \dot{\Psi}^2 \sin^2 \Theta + W^2 + 2W \dot{\Theta} \sin \Theta \right)$$

$$U = m g Z = m g \left(R \cos \Theta + W \right)$$

$$L = T - U$$

$$\frac{d}{dt} \frac{\partial \mathcal{Y}}{\partial \dot{\phi}} = m \frac{d}{dt} \left(R^{2} \dot{\phi} - V R N m \phi \right) = m \left(R^{2} \dot{\phi} - V R \dot{\phi} \right)$$

$$= \frac{\partial \mathcal{Y}}{\partial \dot{\phi}} = m \left(R^{2} \dot{\phi}^{2} \cos \phi \sin \phi - N R \dot{\phi} \cos \phi \right) + m R R \sin \phi$$

$$= \frac{\partial \mathcal{Y}}{\partial \dot{\phi}} = 0 \implies P \implies 2 S R L L S L H$$

$$= \frac{\partial \mathcal{Y}}{\partial \dot{\phi}} = m R^{2} \sin^{2} \phi \quad \dot{\phi} = P$$

$$= \Rightarrow \dot{\dot{\gamma}} = \frac{P}{m R^{2} \sin^{2} \phi}$$

$$= \frac{P^{2} \cos \phi}{m^{2} R^{2} \sin^{2} \phi} + g R \sin \phi$$

$$= \frac{P^{2} \cos \phi}{m^{2} R^{2} \sin^{2} \phi} + g R \sin \phi$$

$$= \frac{P^{2} \cos \phi}{\cos \phi} + g R \sin \phi$$

$$= \frac{N m^{4} \phi}{\cos \phi} = -\frac{P^{2}}{m^{2} R^{3} g}$$